

Whitehead's classical algorithm for subgroups

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McGill seminar, Montreal

Oct. 20th, 2010.

Outline

- 1 The classical Whitehead algorithm
- 2 The bijection between subgroups and automata
- 3 Whitehead algorithm for subgroups
- 4 Whitehead minimization for subgroups in polynomial time

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Definitions and notation

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Whitehead problem

Whitehead Problem

For a group G , find an algorithm s.t. given $u, v \in G$ decides whether there exists $\varphi \in \text{Aut}(G)$ such that $\varphi(u) = v$.

Theorem (Whitehead, 30's)

Whitehead problem is solvable in F_A .

“Proof”:

First part: reduce $\|u\|$ and $\|v\|$ as much as possible by applying autos:

$$u \rightarrow u_1 \rightarrow u_2 \rightarrow \cdots \rightarrow u',$$

$$v \rightarrow v_1 \rightarrow v_2 \rightarrow \cdots \rightarrow v'.$$

Second part: analyze who is image of who by some auto, in the (finite!) sphere of given radius n , $S_n = \{w \in F_k \mid \|w\| = n\}$. \square

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Whitehead minimization in polynomial time

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Whitehead automorphisms are those of the form:

$$\begin{aligned} F_A &\rightarrow F_A \\ a_i &\mapsto a_i && \text{(the multiplier)} \\ a_i \neq a_j &\mapsto a_i^{\epsilon_j} a_j a_i^{\delta_j} \end{aligned}$$

where $\epsilon_j = 0, -1$ and $\delta_j = 0, 1$ (there are $\sim k \cdot 4^k$ many, where $k = |A|$).

Theorem (Roig, V., Weil, 2007)

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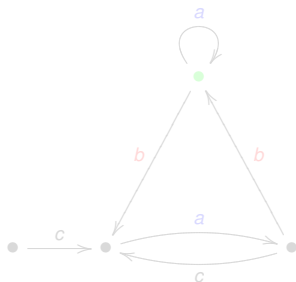
Stallings automata

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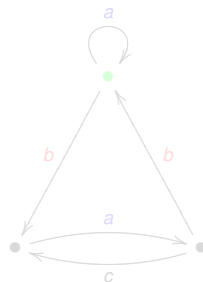
A *Stallings automaton* is a finite A -labeled oriented graph with a distinguished vertex, (X, v) , such that:

- 1- X is connected,
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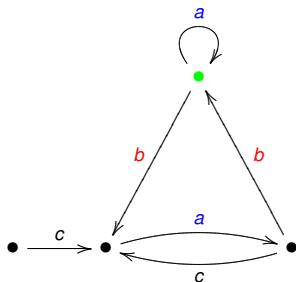
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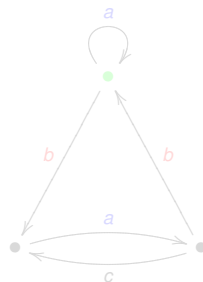
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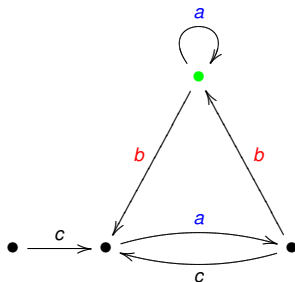
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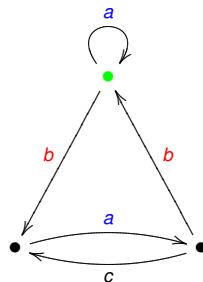
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Stallings (building on previous works) gave a **bijection** between finitely generated subgroups of F_A and Stallings automata:

$$\{\text{f.g. subgroups of } F_A\} \longleftrightarrow \{\text{Stallings automata}\},$$

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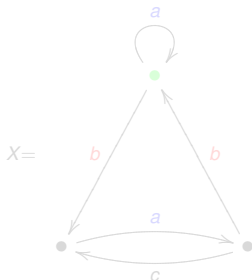
Reading the subgroup from the automata

Definition

To any given (Stallings) automaton (X, v) , we associate its *fundamental group*:

$$\pi(X, v) = \{ \text{labels of closed paths at } v \} \leq F_A,$$

clearly, a subgroup of F_A .



$$\pi(X, \bullet) = \{1, a, a^{-1}, bab, bc^{-1}b, babab^{-1}cb^{-1}, \dots\}$$

$$\pi(X, \bullet) \not\ni bc^{-1}bcaa$$

Membership problem in $\pi(X, \bullet)$ is solvable.

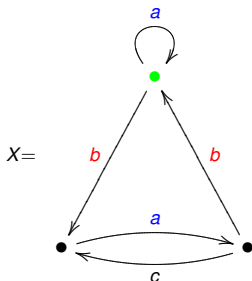
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A basis for $\pi(X, v)$

Proposition

For every Stallings automaton (X, v) , the group $\pi(X, v)$ is free of rank $rk(\pi(X, v)) = 1 - |VX| + |EX|$.

Proof:

- Take a maximal tree T in X .
- Write $T[p, q]$ for the geodesic (i.e. the unique reduced path) in T from p to q .
- For every $e \in EX - ET$, $x_e = \text{label}(T[v, \iota e] \cdot e \cdot T[\tau e, v])$ belongs to $\pi(X, v)$.
- Not difficult to see that $\{x_e \mid e \in EX - ET\}$ is a basis for $\pi(X, v)$.
- And,
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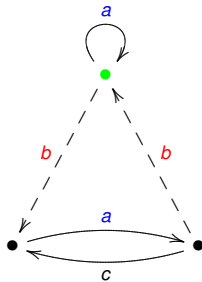
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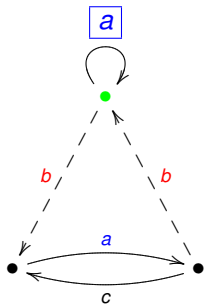
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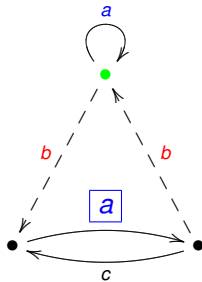
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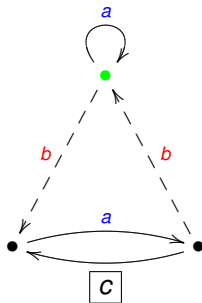
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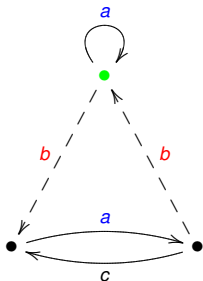
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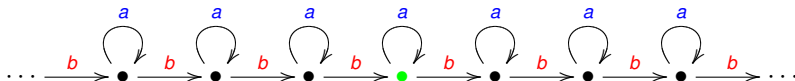
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$$H = \langle a, bab, b^{-1}cb^{-1} \rangle$$
$$rk(H) = 1 - 3 + 5 = 3.$$

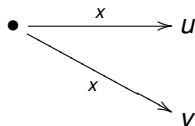
Example-2



$$F_{\mathbb{N}_0} \simeq H = \langle \dots, b^{-2}ab^2, b^{-1}ab, a, bab^{-1}, b^2ab^{-2}, \dots \rangle \leq F_2.$$

Constructing the automata from the subgroup

In any automaton containing the following situation, for $x \in A^{\pm 1}$,



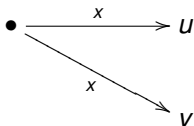
we can **fold** and identify vertices u and v to obtain



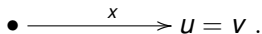
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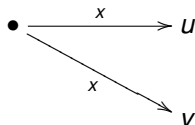
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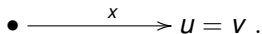
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Lemma (Stallings)

If $(X, v) \rightsquigarrow (X', v')$ is a Stallings folding then $\pi(X, v) = \pi(X', v')$.

Given a f.g. subgroup $H = \langle w_1, \dots, w_m \rangle \leq F_A$ (we assume w_i are reduced words), do the following:

- 1- Draw the flower automaton,*
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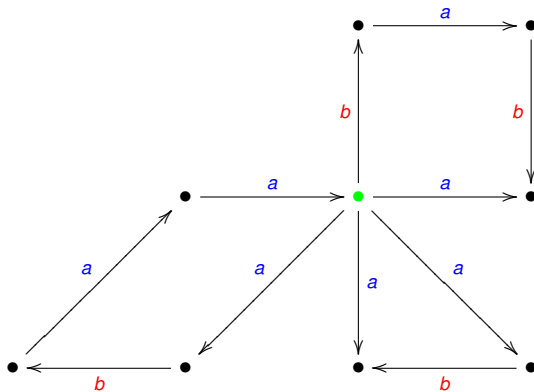
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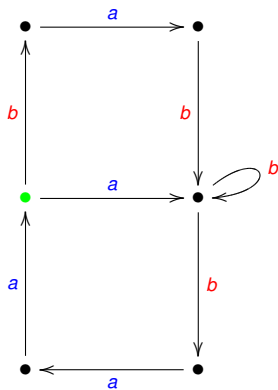
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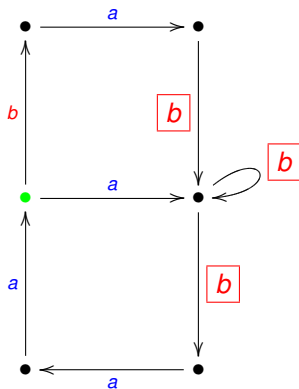
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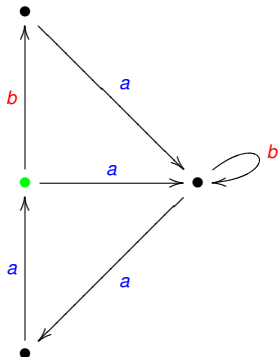
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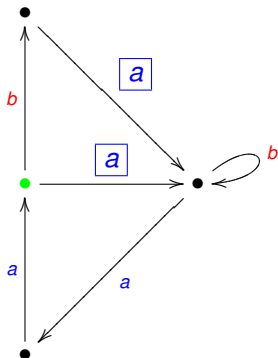
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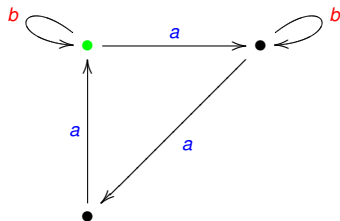
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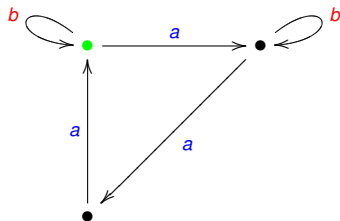


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By Stallings Lemma, $\pi(\Gamma(H), \bullet) = \langle baba^{-1}, aba^{-1}, aba^2 \rangle$

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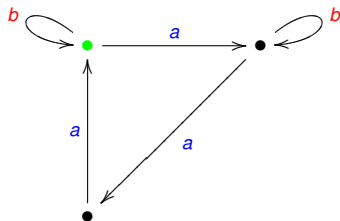


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$$\begin{aligned} \text{By Stallings Lemma, } \pi(\Gamma(H), \bullet) &= \langle baba^{-1}, aba^{-1}, aba^2 \rangle \\ &= \langle b, aba^{-1}, a^3 \rangle \end{aligned}$$

Local confluence

It can be shown that

Proposition

The automaton $\Gamma(H)$ *does not depend* on the sequence of foldings

Proposition

The automaton $\Gamma(H)$ *does not depend* on the generators of H .

Theorem

The following is a bijection:

$$\begin{array}{ccc} \{f.g. \text{ subgroups of } F_A\} & \longleftrightarrow & \{\text{Stallings automata}\} \\ H & \rightarrow & \Gamma(H) \\ \pi(X, v) & \leftarrow & (X, v) \end{array}$$

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Every subgroup of F_A is free.

- Finite automata work for the finitely generated case, but everything extends easily to the general case (using infinite graphs).
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Outline

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- 2 The bijection between subgroups and automata
- 3 Whitehead algorithm for subgroups**
- 4 Whitehead minimization for subgroups in polynomial time

Peak reduction for subgroups

Definition

For $H \leq F_A$, we define $\|H\| = \#V(\Gamma'(H))$.

For a cyclic word w , it is clear that $\|w\| = \|\langle w \rangle\|$.

Definition

A *peak* in F_A is a trio (H, σ, τ) where $H \leq_{\text{fg}} F_A$, $\sigma, \tau \in W_I \cup W_{II}$, such that $\|\sigma(H)\| \leq \|H\|$ and $\|\tau(H)\| \leq \|H\|$ with at least one inequality strict.

Lemma (Peak reduction for subgroups)

For every peak (H, σ, τ) there exists $s \geq 1$ and $\rho_1, \dots, \rho_s \in W_I \cup W_{II}$ such that

- $\tau\sigma^{-1} = \rho_s \cdots \rho_1$,
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Whitehead algorithm for subgroups

Then all the arguments and algorithms extend naturally to this more general context...

Theorem (“Gersten”, 1984)

Given two subgroups $H, K \leq_{\text{fg}} F_A$, it is decidable whether there exists $\varphi \in \text{Aut}(F_A)$ such that $\varphi(H) = K$.

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Whitehead's hypergraph

Thinking a cyclically reduced word w as the circle $\Gamma'(\langle w \rangle)$, its Whitehead graph $Wh(u)$ just describes the **in-links** of the vertices.

Definition

Let $H \leq F_k$ be a f.g. subgroup, and let $\Gamma'(H)$ be its core graph. We define the *Whitehead hyper-graph* of H , denoted $Wh(H)$, as:

- vertices: $A^{\pm 1}$,
- hyper-edges: for every vertex v in $\Gamma'(H)$, put a hyper-edge consisting on the *in-link* of v .

Lemma (Roig, V., Weil, 2007)

Given a f.g. subgroup $H \leq F_k$ and a Whitehead automorphism α , think α as a cut in $Wh(H)$, say $\alpha = (T, a)$, and then

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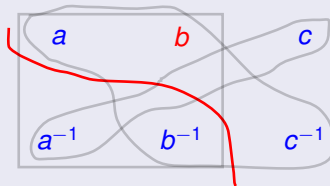
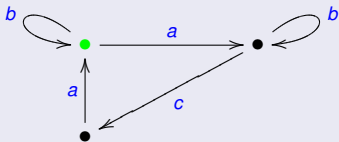
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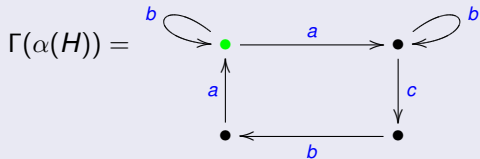
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Consider $H = \langle b, aba^{-1}, aca \rangle \leq F_3$. Its core graph $\Gamma(H)$, and Whitehead hyper-graph $Wh(H)$ are:



In fact, $\alpha(H) = \langle b, aba^{-1}, acbab \rangle$ and then



and so, $4 - 3 = \|\alpha(H)\| - \|H\| = 3 - 2$.

Minimizing capacities in hyper-graphs

So, Whitehead's Minimization Problem for subgroups reduces to:

- *run over all possible multipliers, say a , (there are $2k$),*
- *find an (a, a^{-1}) -cut with minimal possible capacity in the given hyper-graph.*

Unfortunately, there is no analog of max-flow min-cut algorithm for hyper-graphs ...

...but it is still possible to find minimal cuts in polynomial time because of sub-modularity:

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Efficient minimization of sub-modular functions is an active research topic in computer science. One of the classical results is the following

Proposition

There exists a algorithm which, given a sub-modular function $f: \mathcal{P}(V) \rightarrow \mathbb{N}$ computes its minimum with a number of queries to evaluate f bounded above by a polynomial on $|V|$.

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